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Some terminology

Discrimination measures

Correcting to overfitting

measures

Prognostic modeling

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Medical gnosis

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Miettinen (2011, p. 18):

Medicine - A professional's pursuit and attainment of esoteric knowing about the health of the client - medical gnosis, that is - and teaching the client (or a representative of the client) accordingly. (Anything else - intervention, most notably - is incidental to, and not in the essence of, medicine; i.e., it is not always true of, and unique to, medicine.)

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 - 2. Prognosis

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- ▶ The three subtypes of medical knowing are:
 - 1. Diagnosis
 - 2. Prognosis
 - 3. Etiognosis

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Prognosis

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Prognosis

▶ Prognosis is defined by Miettinen (2011, p. 22) as

Prognosis - A doctor's esoteric knowing about the future course and/or outcome of a/the client's health, specifically in respect to a particular illness (cf. 'Diagnosis' and 'Etiognosis')

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Prognosis - A doctor's esoteric knowing about the future course and/or outcome of a/the client's health, specifically in respect to a particular illness (cf. 'Diagnosis' and 'Etiognosis')

► This can involve knowing about whether a currently absent illness will occur in the future, or the outcome of an already existing illness. Miettinen (2011, p. 23):

Clinical prognosis - A doctor's (clinician's) esoteric knowing about whether a particular, currently absent illness (overt) will occur; also: regarding an already- existing illness, such knowing (probabilistic) about an adverse event/state (treatment induced perhaps) in its course and/or as its outcome

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Prognostic factors

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Prognostic factors

► However, the established terminology makes a distinction between 'prognostic factors' and 'risk factors'.

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- ► However, the established terminology makes a distinction between 'prognostic factors' and 'risk factors'.
- When referring to markers, rather than possible causal factors, terms 'prognostic indicators' and 'risk indicators' might be more appropriate. Miettinen (2011, p. 93):

Prognostic indicators for adverse events/states are properly termed risk indicators; they need not be risk factors.

Prognostic factors

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► Sometimes 'predictive factor' is used to refer to something that predicts response to a treatment (again, not necessarily causal, so different from 'effect modifier'). A factor can be both prognostic and predictive in this sense.

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Good prognosis?

Miettinen (2011, p. 14):

Good diagnosis/etiognosis/prognosis - One with probability close to that of correct diagnosis/etiognosis/prognosis.

Note: 'Good prognosis' is commonly attributed to an illness, as a common misnomer for not-so-bad course, 'bad prognosis' being its corresponding misnomer for bad course.

However, prognosis actually is a cognitive entity, possible only for a doctor to have; as the illness of a doctor's patient does not have a mind, it cannot have prognosis.

Good prognosis?

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Importantly, good prognosis in this sense does not require knowing the patient's outcome with certainty.

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Prognostic probabilities

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Prognostic probabilities

► Miettinen (2011, p. 22):

Note 2: Clinical prognosis is knowing about the correct probability of the event's occurring or the state being present in/at a particular period/point of prognostic time. Correct prognosis is characterized by this probability. which represents the proportion of instances of the profile in general (in the abstract) such that, given the intervention, the event/state would occur in/at that period/point of prognostic time. (That proportion is implied by a suitable prognostic probability function.)

Prognostic probabilities

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We can obtain such prognostic probability functions by fitting a suitable survival model.

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Prognostic probabilities (2)

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Prognostic probabilities (2)

▶ In the absence of competing causes (e.g. when the event of interest is death due to any cause), the prognostic probability is simply the *s*-year risk of the event occurring:

$$\pi_i(s) = 1 - \exp\{-\Lambda_i(s)\}.$$

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► For example, using a Cox model, this could be estimated as

$$\hat{\pi}_i(s) = 1 - \exp\left\{-\hat{\mathsf{\Lambda}}_0(s)\exp\{\hat{eta}'x_i\}
ight\},$$

where x_i are the predictors available at the time of prediction (remember, we cannot use future information here), and $\hat{\Lambda}_0(s)$ is given by the Breslow estimator.

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where x_i are the predictors available at the time of prediction (remember, we cannot use future information here), and $\hat{\Lambda}_0(s)$ is given by the Breslow estimator.

Note that we don't predict risks; we predict the outcome event using the risk as the measure.

Cox model for CVD incidence: Classic risk factors

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```
Call:
coxph(formula = Surv(evtime, cvd) ~ agestart + hdla + nonhdl +
    systm + dsmoker + hisdiab + cvdrugs + bmi)
```

n= 2235, number of events= 227

```
coef exp(coef)
                             se(coef)
                                          z Pr(>|z|)
                             0.023430 2.462 0.013815 *
         0.057685
                   1.059381
agestart
hdla
        -0.727299
                   0.483212
                             0.248552 -2.926 0.003432 **
nonhdl
         0.213089
                   1.237495
                             0.065036 3.276 0.001051 **
systm
         0.013459
                   1.013550
                             0.003123 4.310 1.63e-05 ***
dsmoker
         0.653927
                   1.923078
                             0.141063 4.636 3.56e-06 ***
hisdiab
         1.082912
                   2.953267
                             0.311534 3.476 0.000509 ***
                   1.140196
cvdrugs
         0.131201
                             0.201610 0.651 0.515199
bmi
         0.012835
                   1.012917
                             0.020518 0.626 0.531613
```

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Cox model for CVD incidence: Classic risk factors + IL-1RA

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```
Call:
coxph(formula = Surv(evtime, cvd) ~ agestart + hdla + nonhdl +
    systm + dsmoker + hisdiab + cvdrugs + bmi + il1ra)
```

n= 2235, number of events= 227

```
coef exp(coef)
                              se(coef)
                                            z Pr(>|z|)
agestart
          0.059676
                    1.061492
                              0.023376
                                        2.553 0.010684 *
hdla
         -0.664484
                    0.514539
                              0.247980 - 2.680 \ 0.007371 **
nonhdl
         0.215680
                    1.240705
                              0.064776 3.330 0.000870 ***
          0.013085
                    1.013171
                              0.003142 4.164 3.12e-05 ***
systm
dsmoker
          0.628657
                    1.875091
                              0.141404 4.446 8.76e-06 ***
hisdiab
          1.041591
                    2.833723
                              0.312358
                                        3.335 0.000854 ***
cvdrugs
          0.066795
                    1.069076
                              0.204943
                                        0.326 0.744485
bmi
          0.001686
                    1.001688
                              0.020857
                                        0.081 0.935558
il1ra
          0.139281
                    1.149447
                              0.049377
                                        2.821 0.004791 **
```

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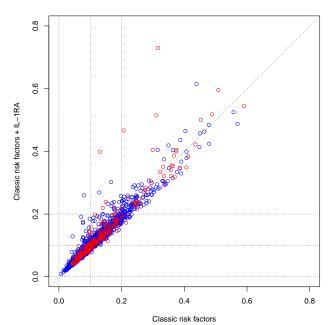
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10-year risks from the two models



Competing causes

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Competing causes

When we are not looking at all-cause mortality, but say, cause-specific mortality, in principle we have to take into account that a death due to a specific cause is preceded by survival from all causes. Olli Saarela

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Competing causes

- When we are not looking at all-cause mortality, but say, cause-specific mortality, in principle we have to take into account that a death due to a specific cause is preceded by survival from all causes.
- ▶ In this case, the risk of event type *j* occurring first is obtained from the cause-specific cumulative incidence function:

$$\pi_{ij}(s) = \int_0^s \lambda_{ij}(t) S_i(t) dt,$$

where

$$S_i(t) = \exp\left\{-\sum_{j=1}^J \Lambda_{ij}(t)
ight\}$$

is the overall survival function.

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Competing causes

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is the overall survival function.

► Each one of the cause-specific cumulative hazard functions could be estimated through a Cox model as

$$\hat{\Lambda}_{ii}(t) = \hat{\Lambda}_{0i}(t) \exp{\{\hat{\beta}_i' x_i\}}.$$

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Model validation

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Model validation

▶ How good are the risks $\hat{\pi}_i(s)$ in predicting the outcome?

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Model validation

- ▶ How good are the risks $\hat{\pi}_i(s)$ in predicting the outcome?
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Model validation

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- Validation can be either internal (using the same dataset where the model was fitted), or external (using an independent dataset for validation).

Model validation

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- Validation can be either internal (using the same dataset where the model was fitted), or external (using an independent dataset for validation).
- ► Two particular aspects of 'goodness' of the predictions would be how well they discriminate between those who will experience an event in the future and those who don't (discrimination), and how well the predictions match with the observed level of risk in different subgroups (calibration).

Sensitivity and PPV

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Sensitivity and PPV

Let π^* be a given threshold risk, maybe related to a clinical decision to treat or not treat the patient.

Discrimination measures

Sensitivity and PPV

- Let π^* be a given threshold risk, maybe related to a clinical decision to treat or not treat the patient.
- ▶ In the absence of censoring, sensitivity could be defined as the probability that an individual who will experience the outcome event will have an estimated risk above the threshold (true positive), that is,

$$P(\hat{\pi}_i(s) \geq \pi^* \mid N_i(s) = 1).$$

Discrimination measures

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Calibration measures

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▶ At this point we have fixed the risk model parameters to their estimates, so the probability here refers to the probability of individual *i* having predictor values that give a risk above the threshold.

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Sensitivity and PPV

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- ▶ At this point we have fixed the risk model parameters to their estimates, so the probability here refers to the probability of individual *i* having predictor values that give a risk above the threshold.
- An alternative measure would be the positive predictive value

$$P(N_i(s) = 1 \mid \hat{\pi}_i(s) \geq \pi^*).$$

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Specificity and NPV

Sensitivity reflects how well the risk model identifies the individuals who will experience the event. On the other hand, specificity reflects how well the model identifies those who will not (true negative). This is the probability

$$P(\hat{\pi}_i(s) < \pi^* \mid N_i(s) = 0).$$

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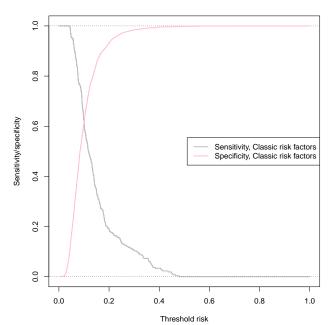
► An alternative measure would be the negative predictive value

$$P(N_i(s) = 0 \mid \hat{\pi}_i(s) < \pi^*).$$

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Discrimination measures

Sensitivity and specificity curves



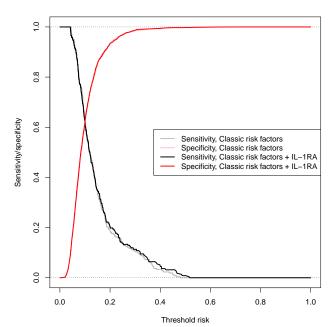
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Sensitivity and specificity curves



ROC curve

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ROC curve

▶ There is a tradeoff between sensitivity and specificity; higher values of the threshold π^* give better specificity, but worse sensitivity, and vice versa. (Why?)

ROC curve

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Discrimination measures

Correcting fo overfitting

- ► There is a tradeoff between sensitivity and specificity; higher values of the threshold π^* give better specificity, but worse sensitivity, and vice versa. (Why?)
- Since we usually don't have a well-established threshold risk, we would usually calculate the sensitivity and 1-specificity (i.e. false positive probability) at all possible values of π^* and present these as a curve. The result is known as the receiver operating characteristics (ROC) curve.

Discrimination measures

Correcting fo overfitting

- There is a tradeoff between sensitivity and specificity; higher values of the threshold π^* give better specificity, but worse sensitivity, and vice versa. (Why?)
- Since we usually don't have a well-established threshold risk, we would usually calculate the sensitivity and 1-specificity (i.e. false positive probability) at all possible values of π^* and present these as a curve. The result is known as the receiver operating characteristics (ROC) curve.
- Note that when the predictors in the model have no prognostic value whatsoever, we have that $TPP = P(\hat{\pi}_i(s) \geq \pi^* \mid N_i(s) = 1) = P(\hat{\pi}_i(s) \geq \pi^*) \text{ and } FPP = P(\hat{\pi}_i(s) \geq \pi^* \mid N_i(s) = 0) = P(\hat{\pi}_i(s) \geq \pi^*),$ which means that the ROC curve is a diagonal line.

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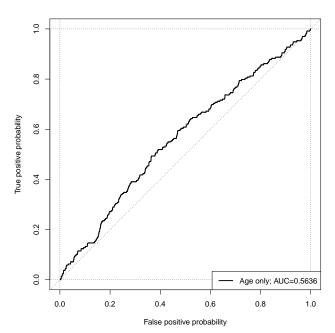
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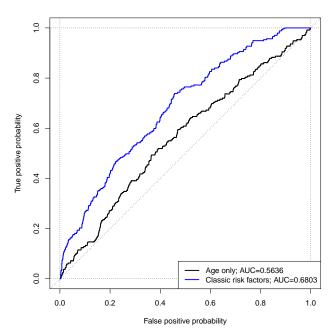
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ROC curves

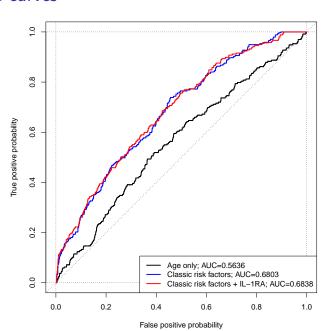
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AUC

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Calibration

► The area under the curve has a probabilistic interpretation, namely that the model correctly orders the risks of two individuals with and without an event, that is,

$$P(\hat{\pi}_i(s) > \hat{\pi}_j(s) \mid N_i(s) = 1, N_j(s) = 0).$$

Discrimination measures

AUC

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• If AUC = 1, the model can always discriminate between the individuals with and without an event.

Discrimination measures

AUC

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- For non-censored event times, an analogous measure could be defined as

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Calibration measures The area under the curve has a probabilistic interpretation, namely that the model correctly orders the risks of two individuals with and without an event, that is,

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▶ How to estimate this in the presence of censoring?

c-index

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c-index

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▶ One possible solution: compare only those censored/non-censored pairs where the observed time T_j of the censored individual j is longer than the observed time T_i of the non-censored individual i.

Discrimination measures

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Discrimination measures

Correcting for overfitting

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Discrimination measures

Correcting for overfitting

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- ▶ The resulting statistic is known as the concordance index, or c-index (Harrell et al. 1996), and is calculated automatically in the R coxph output.
- ► This can also be calculated using the survConcordance function of the survival package.

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ROC curves and censoring

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ROC curves and censoring

► How can we estimate sensitivity and specificity in the presence of censoring?

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ROC curves and censoring

- How can we estimate sensitivity and specificity in the presence of censoring?
- ▶ Heagerty et al. (2000): use Bayes formula to get

$$\begin{aligned} & P(\hat{\pi}_i(s) \geq \pi^* \mid N_i(s) = 1) \\ & = \frac{[1 - P(N_i(s) = 0 \mid \hat{\pi}_i(s) \geq \pi^*)][1 - P(\hat{\pi}_i(s) < \pi^*)]}{1 - P(N_i(s) = 0)} \end{aligned}$$

and

$$P(\hat{\pi}_i(s) < \pi^* \mid N_i(s) = 0)$$

$$= \frac{P(N_i(s) = 0 \mid \hat{\pi}_i(s) < \pi^*)P(\hat{\pi}_i(s) < \pi^*)}{P(N_i(s) = 0)}.$$

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ROC curves and censoring

- How can we estimate sensitivity and specificity in the presence of censoring?
- ▶ Heagerty et al. (2000): use Bayes formula to get

$$P(\hat{\pi}_{i}(s) \geq \pi^{*} \mid N_{i}(s) = 1)$$

$$= \frac{[1 - P(N_{i}(s) = 0 \mid \hat{\pi}_{i}(s) \geq \pi^{*})][1 - P(\hat{\pi}_{i}(s) < \pi^{*})]}{1 - P(N_{i}(s) = 0)}$$

and

$$P(\hat{\pi}_i(s) < \pi^* \mid N_i(s) = 0)$$

$$= \frac{P(N_i(s) = 0 \mid \hat{\pi}_i(s) < \pi^*)P(\hat{\pi}_i(s) < \pi^*)}{P(N_i(s) = 0)}.$$

▶ Here the probabilities $P(N_i(s) = 0 \mid \cdot)$ can be estimated through the Kaplan-Meier method (R package survivalROC), and $P(\hat{\pi}_i(s) < \pi^*)$ through the ECDF of the risks.

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Correcting for overfitting

Validating the model in the same dataset where it was fitted ('trained') will generally result in overoptimistic results. Correcting for

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Correcting for overfitting

- Validating the model in the same dataset where it was fitted ('trained') will generally result in overoptimistic results.
- Ideally we would like to have a separate training and validation datasets, but in the absence of this, we can calculate the risks as

$$\hat{\pi}_i(s) = 1 - \exp\left\{-\hat{\Lambda}_{0(-i)}(s) \exp\{\hat{\beta}'_{(-i)}x_i\}\right\},\,$$

where $\hat{\Lambda}_{0(-i)}$ and $\hat{\beta}_{(-i)}$ are the baseline cumulative hazard and regression parameter estimates when observation i has been removed from the data. This is repeated for each $i=1,\ldots,n$.

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- ► This procedure is known as leave-one-out cross-validation; now the same observation is never used for both fitting the model, and for validating it.
- ▶ This is a special case of *k*-fold cross-validation.

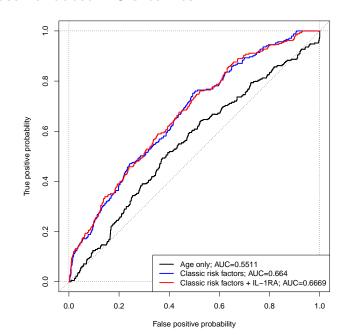
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Cross-validated ROC curves



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Model building and overfitting

Penalized regression (such the LASSO), and stepwise regression (for example using the AIC information criterion as the stopping rule) are options for screening a large number of new markers.

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Model building and overfitting

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- ► The risk/prognostic factors in the baseline model are not penalized/selected.
- ▶ When combined with leave-one-out or *k*-fold cross validation, any model selection procedure would have to be applied in each training set.

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▶ A standard way to check for model calibration would be to divide the data into *K* (say, 10) groups based on deciles of the risk estimates, and compare the expected and observed numbers of events in these groups.

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- ▶ A standard way to check for model calibration would be to divide the data into *K* (say, 10) groups based on deciles of the risk estimates, and compare the expected and observed numbers of events in these groups.
- ► The comparison can be made using the Hosmer-Lemeshow test statistic:

$$\sum_{k=1}^{K} \frac{(O_k - E_k)^2}{N_k \bar{\pi}_k (1 - \bar{\pi}_k)} \sim \chi_{K-2}^2.$$

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- In the presence of censoring, O_k could be estimated as $O_k \approx N_k[1 \hat{S}_k(s)]$, where $\hat{S}_k(s)$ is the Kaplan-Meier survival probability in group k.
- ▶ The expected and observed counts E_k and O_k can also be compared visually.

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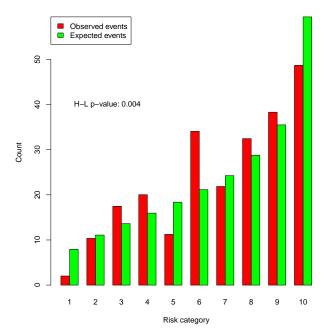
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Calibration plot: Classic risk factors



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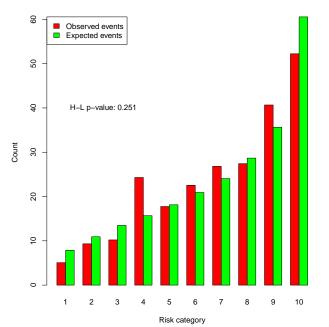
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Calibration plot: Classic risk factors + IL-1RA



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